

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property
Organization
International Bureau



(43) International Publication Date
8 July 2004 (08.07.2004)

PCT

(10) International Publication Number
WO 2004/056537 A2

(51) International Patent Classification⁷: B25J 9/00

(21) International Application Number:
PCT/IB2003/005646

(22) International Filing Date: 4 December 2003 (04.12.2003)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
60/434,549 19 December 2002 (19.12.2002) US

(71) Applicant (for all designated States except US): KONINKLIJKE PHILIPS ELECTRONICS N.V. [NL/NL]; Groenewoudseweg 1, NL-5621 BA Eindhoven (NL).

(72) Inventors; and

(75) Inventors/Applicants (for US only): ALSAFADI, Yasser [US/US]; P.O. Box 3001, Briarcliff Manor, NY 10510-8001 (US). CHIPARA, Octav [US/US]; P.O. Box 3001, Briarcliff Manor, NY 10510-8001 (US). YASSIN, Amr [US/US]; P.O. Box 3001, Briarcliff Manor, NY 10510-8001 (US).

(74) Common Representative: KONINKLIJKE PHILIPS ELECTRONICS N.V.; c/o Keegan, Frank, P.O. Box 3001, Briarcliff Manor, NY 10510-8001 (US).

(81) Designated States (national): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SY, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.

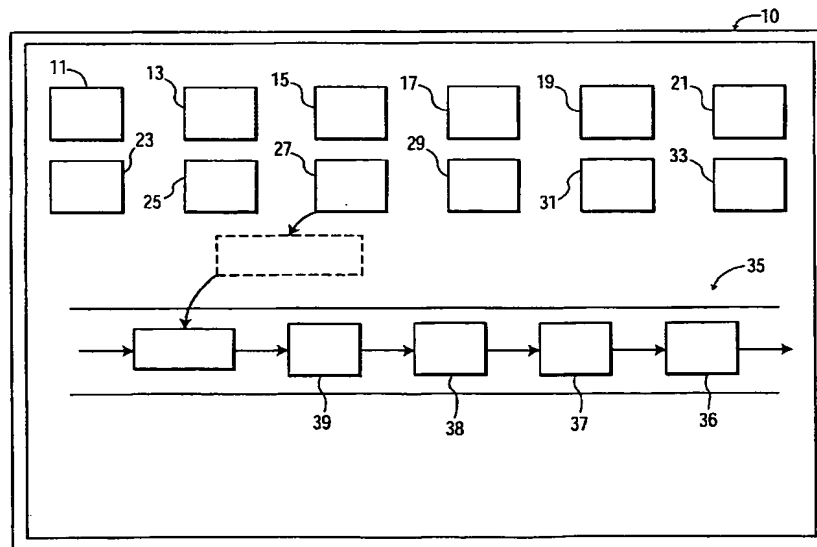
(84) Designated States (regional): ARIPO patent (BW, GH, GM, KE, LS, MW, MZ, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IT, LU, MC, NL, PT, RO, SE, SI, SK, TR), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Declaration under Rule 4.17:

— as to applicant's entitlement to apply for and be granted a patent (Rule 4.17(ii)) for the following designations AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, BZ, CA, CH,

[Continued on next page]

(54) Title: SYSTEM AND METHOD FOR CONTROLLING A ROBOT



(57) **Abstract:** The present invention is directed to a computer-implemented system and method for controlling robots (41) using a high-level programming language. The invention defines three programming languages, i.e., two high-level languages and a low-level language. A first high-level programming language is referred to herein as a robot scenario language (RSL) (20), in which an end-user (18) creates a robotic presentation (40) in terms of high-level behaviors or actions. A second high-level language, referred to herein as a robot behavior language (RBL) comprised of templates for describing how each high level behavior or action in the high-level (RSL) language is to be transformed or mapped into low-level language commands for directly controlling the hardware of the robot (41). The low-level language referred to herein as a robot hardware language (RHWL).